Design and Analysis of Algorithm Complexity Analysis

- Notions of Algorithm and Time Complexity
- Pseudocode of Algorithm
- 3 Asymptotic Order of Function
- 4 Important Function Class
- 5 Survey of Common Running Times

Outline

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Problem and Solution

Problem Description.

- A group of parameters that specify the problem (set, variable, function, sequences, etc.), include descriptions of domain and relation among them
- Definition of Solution: determined by optimization objective or constraints

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Instance. An assignment of parameters \rightarrow an instance of problem

Algorithm

Definition 1 (Algorithm)

An algorithm ${\cal A}$ is a finite sequence of well-defined, computer implementable instructions that solve a class of problems

- algorithms are always unambiguous
- specifications for performing calculations, data processing, automated reasoning, and other tasks.

Algorithm \mathcal{A} for Problem P

- ullet take any instance of P as \mathcal{A} 's input, computation of each step is deterministic
- ullet ${\cal A}$ halts in finite steps
- always output the correct solution

Basic Computer Steps and Input Size

An insightful analysis is based on the right simplifications.

Basic computer steps. capture abstract atomic operation

Example. compare, add, multiplication, swap, assign . . .

This is the first important simplification!

Input size. capture the scale of instance: proportional to the length of instance encoding string

 Example. number of array, number of scheduling tasks, number of vertices and edges

Examples of Input Size and Basic Computer Steps (1/2)

Sorting. array a[n]

- n: the number of elements in the array
- element compares and movement

Searching. search x in array a[n]

- n: the number of elements in the array
- \bullet element compares between x and a[i]

Integer multiplication. $a \times b$

- ullet the binary length of a and b, a.k.a. $m=\log_2 a$, $n=\log_2 b$
- bit-wise multiplication $-a \times b$ requires #mn bit-wise multiplication

Examples of Input Size and Basic Computer Steps (2/2)

Matrix multiplication. $\mathbf{A}_{n_1 \times n_2} \cdot \mathbf{B}_{n_2 \times n_3}$

- ullet dimensions of ${f A}$ and ${f B}$, a.k.a. n_1,n_2,n_3
- point-wise multiplication ${\bf A}\cdot {\bf B}$ requires $n_1n_2n_3$ -times point-wise multiplication
- $n_1 = n_2 = n_3 = n \sim n^3$

Graph visit.
$$G = (V, E)$$

- number of vertices and edges
- assignment of flag variable

Measurement of Algorithm's Efficiency

Express running time by counting the number of basic computer steps as a function of the size of the input.

uncluttered, machine-independent characterization

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uncluttered, machine-independent characterization

For different inputs of the same instance size, the number of basic computer steps might vary \Rightarrow functions could be different

Choose which one?

I am prepared for the worst, but hope for the best.

— Benjamin Disraeli

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Worst-case. Maximum running time for any input of size n.

Example. Quicksort requires at most n^2 compares to sort n elements.

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Best-case. Minimum running time for all inputs of size n

Example. Insertion sort only requires n compares when the input is sorted already.

Average-case. Expected running time for a random input of size n

Example. expected number of element compares of Quicksort is $\sim n \log n.$

About Worst-Case

Algorithm. Some exponential-time algorithms are used widely in practice because the worst-case instances seem to be rare.

• Linux grep command

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About Worst-Case

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Cryptography. Require hard instance to be efficiently samplable — problems only have high worst-case complexity may not be suitable to be used as hardness assumption

Good news to Algorithms = Bad news to Cryptography Win-Win flavor

Formula of A(n)

A(n): average-case complexity

- Let X be the set of all inputs of size n, $\Pr[x \in X] = p(x)$
- t(x): the number of basic operations that ${\mathcal A}$ performs on input x

$$A(n) = \sum_{x \in X} p(x)t(x)$$

In many cases, we assume the input distribution is a uniform distribution.

Example of Search

Search Problem

Input. Array a[n] with ascending order, search \boldsymbol{x}

Output. $j \in [0, \ldots, n]$

- ullet if $x \in a[n]$, then j is the first index such that a[j] = x
- else, j=0

Basic operation. element compare between x and a[i]

Sequential Search Algorithm

```
Algorithm 1: Search(a[n], x)
1: flag \leftarrow 0;
2: for j=1 to n do
3:
  if a[j] = x then
4: flag = 1;
         break;
5:
     end
6.
7: end
8: if f lag = 0 then j = 0;
9: return j;
```

```
Example. 1,2,3,4,5
```

- x = 4: 4 compares
- x = 2.5: 5 compares

Worst-case Complexity

There are 2n + 1 types different inputs:

- Case inside: $x = a[1], x = a[2], \dots, x = a[n]$
- Case outside: $x < a[1], a[1] < x < a[2], \dots, a[n] < x$

Worse-case input. $x \notin A \lor x = A[n]$, requires n compares

Worse-case complexity. T(n) = n

Average-case complexity

Assume $\Pr[x \in A] = p$, and distributes on each position with equal probability.

$$T(n) = \sum_{i=1}^n i \cdot \frac{p}{n} + (1-p)n \text{ //sum of arithmetic sequence}$$

$$= \frac{p(n+1)}{2} + (1-p)n$$

When p = 1/2

$$T(n) = \frac{n+1}{4} + \frac{n}{2} \approx \frac{3n}{4}$$

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Pseudocode of Algorithm

Definition 2 (Pseudocode)

An informal high-level description of the operating principle of algorithms: uses the structural conventions of programming language, but is intended for human reading rather than machine reading.

Instruction	Symbol
Assignment	← or :=
Branch statement	ifthen[else]
Loop structure	while, for, repeat until
Transfer statement	goto
Return statement	return
Function call	Func()
Comment	// or /* */

Example: Euclid Algorithm for Greatest Common Divisor

Algorithm 2: EuclidGCD(n, m)

```
Input: n, m \in \mathbb{Z}^+, n \ge m
Output: GCD(n, m)
```

1: while m > 0 do

2: $r \leftarrow n \mod m$;

3: $n \leftarrow m$;

4: $m \leftarrow r$;

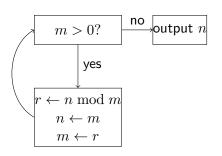
5: **end**

6: return n

Demo: n = 36, m = 15

while	n	m	r
1st loop	36	15	6
2nd loop	15	6	3
3rd loop	6	3	0
	3	0	0

 $\verb"output"\,3$



Example of Insertion Sort

Algorithm 3: Algorithm InsertSort(A[n])

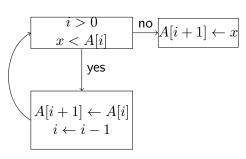
```
Input: array A[n]
  Output: A[n] in ascending order
1: for j \leftarrow 2 to n do
  x \leftarrow A[i]:
3: i \leftarrow j-1 //insert A[j] to A[1...j-1];
4: while i > 0 and x < A[i] do
          A[i+1] \leftarrow A[i];
5:
      i \leftarrow i - 1:
6:
      end
7.
      A[i+1] \leftarrow x;
8.
9: end
```

i is the left neighbor index of the final insert position

Demo of Insertion Sort

$$\begin{array}{|c|c|c|c|c|} \hline 2 & 4 & 1 & 5 & 3 \\ \hline j = 3, & x = A[3] = 1 \\ i = 2, & A[2] = 4 \\ \hline \hline i > 0, & x < A[2] \checkmark \\ \hline \hline 2 & 4 & 4 & 5 & 3 \\ \hline A[3] = 4, & i = 1, & x = 1 \\ \hline i > 0, & x < A[1] \checkmark \\ \hline \hline 2 & 2 & 4 & 5 & 3 \\ \hline A[2] = 2, & i = 0, & x = 1 \\ \hline \end{array}$$

$$i > 0$$
 X 1 2 4 5 3



Example of Binary Merge Sort

Algorithm 4: Algorithm MergeSort(A, l, r)

```
Input: array A[l,r]
Output: A[l,r] in ascending order

1: if l < r then

2: m \leftarrow \lfloor (l+r)/2 \rfloor;

3: MergeSort(A,l,m);

4: MergeSort(A,m+1,r);

5: Merge(A,l,m,r);

6: end
```

MergeSort is a recursive algorithm

call itself from within its own code

Pseudocode of Algorithm ${\cal A}$

Algorithm 5: Algorithm A

```
Input: Array P[0,\ldots,n]\in\mathbb{R}^{n+1},\ x\in\mathbb{R}
Output: y
1: y\leftarrow P[0];\ power\leftarrow 1;
2: for i\leftarrow 1 to n do
3: power\leftarrow power\times x;
4: y\leftarrow y+P[i]\times power;
5: end
6: return y;
```

What do 3-4 compute?

$$\text{for } i \in [n] \xrightarrow{power} \begin{array}{c} power \leftarrow power \times x \\ y \leftarrow y + P[i] \times power \end{array}$$

loop	power	y
0	1	P[0]
1	x	$P[0] + P[1] \times x$
2	x^2	$P[0] + P[1] \times x + P[2] \times x^2$
3	x^3	$P[0] + P[1] \times x + P[2] \times x^2 + P[3] \times x^3$
		•••

Input P[0, ..., n] is the coefficients of n-degree polynomial P(x)

•
$$\mathcal{A}$$
 compute $P(x) = \sum_{i=0}^n P[i] x^i$

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Motivation

We use functions over $\mathbb N$ to capture how the running time or space requirements of algorithms grow as the input size increases.

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How to compare them? How to classify them?

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How to compare them? How to classify them?

The first simplification leads to another. Now, second simplification comes into play, consider the order of function rather than its concrete form.

Big-*O* **Notations**

Paul Bachmann and Edumund Landau invented a family of notations known as Big-O notation to describe the limiting behavior of a function when the input tends towrads infinity.





Figure: Paul Bachmann & Edumund Landau

- also known as Bachmann-Landau or asymptotic notation
- mathematical notation → describe running times

Big-*O* **Notation**

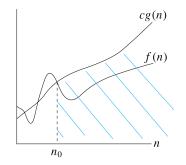
Definition 3 (Big-O)

 $\exists c > 0$, $\exists n_0$, such that $\forall n \geq n_0$:

$$f(n) \le cg(n)$$

f is bounded above by g (up to constant factor) asymptotically

$$f(n) = O(g(n))$$



Limit definition

$$\lim_{n\to\infty}\sup\frac{f(n)}{g(n)}<\infty$$

Some Remarks

Big- ${\cal O}$ notation characterizes functions according to their growth rates: different functions with the same growth rate may be represented using the same ${\cal O}$ notation.

- letter O is used because the growth rate of a function is also referred to as the order of the function.
- ullet there are many (c, n_0) , it suffices to find one tuple
- for finite values $n \leq n_0$, the inequality may not hold
- ullet constant functions can be written as O(1)

More about Big-O

f(n) = O(g(n)): the order of f(n) is less than that of g(n)

Typical usage: give upper bound

• Insertion sort makes $O(n^2)$ compares to sort n elements.

Example 1. $f(n) = n^2 + n$

- $f(n) = O(n^2) \leftarrow \text{choose } c = 2, n_0 = 1$
- $f(n) = O(n^3) \leftarrow \text{choose } c = 1, n_0 = 2$

Example 2. $f(n) = 32n^2 + 17n + 1$

- $f(n) = O(n^2) \leftarrow \text{choose } c = 50, n_0 = 1$
- f(n) is also $O(n^3)$
- f(n) is neither O(n) nor $O(n \log n)$

Limits of Big-*O*

 $\operatorname{Big-}O$ notation only provides an upper bound on the growth rate of the function.

Associated with big-O notation are several related notations, using the symbols o, Ω , ω , and Θ , to describe other kinds of bounds on asymptotic growth rates.

Big- Ω **Notation**

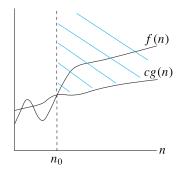
Definition 4 (Big- Ω)

 $\exists c > 0$, $\exists n_0$, $\forall n \geq n_0$:

$$f(n) \ge cg(n)$$

f is bounded below by g asymptotically

$$f(n) = \Omega(g(n))$$



Limit definition

$$\lim_{n \to \infty} \inf \frac{f(n)}{g(n)} > 0$$

Example of Big- Ω

 $f(n) = \Omega(g(n))$: the order of f(n) is greater than g(n).

Typical usage: give lower bound

• Any compare-based sorting algorithm requires $\Omega(n \log n)$ compares in the worst case.

Meaningless statement. Any compare-based sorting algorithm requires at least $O(n \log n)$ compares in the worst case.

ullet $O(\cdot)$ cannot give lower bound

Example. $f(n) = n^2 + n$

- $f(n) = \Omega(n^2) \leftarrow c = 1, n_0 = 1$
- $f(n) = \Omega(100n) \leftarrow c = 1/100$, $n_0 = 1$

Big O and Ω notations are originally used as a tight upper-bound (resp. lower-bound) on the growth of an algorithm's effort But, according to the definitions

g(n) could be a loose upper-bound (resp. lower-bound).

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g(n) could be a loose upper-bound (resp. lower-bound).

To make the role as a tight upper-bound more clear, small o and ω notations are used to describe an upper-bound/lower-bound that cannot be tight.

Small o **Notation**

Definition 5 (Small-o)

 $\forall c > 0$, $\exists n_0$, such that $\forall n \geq n_0$:

$$f(n) < cg(n)$$

f is dominated by g asymptotically:

$$f(n) = o(g(n))$$

Limit definition

$$\lim_{n \to \infty} \frac{f(n)}{g(n)} = 0$$

More about Small-o

 $f(n)=o(g(n))\colon$ the order of f(n) is strictly smaller than that of g(n)

Typical usage. $\log n = o(n)$

Example. $f(n) = n^2 + n$, $f(n) = o(n^3)$

• $c \ge 1$: obviously holds, choose $n_0 = 2 \Rightarrow n^2 + n < cn^3$

$$cn^3 \ge n^3 = n^2((n-1)+1) \ge n^2 + n$$
, when $n \ge n_0$

• 0 < c < 1: choose $n_0 > \lceil 2/c \rceil$, because

$$cn \ge cn_0 \ge 2$$

$$n^2 + n < 2n^2 \le cn \cdot n^2 < cn^3$$

Small ω Notation

Definition 6

 $\forall c > 0$, $\exists n_0$, $\forall n \geq n_0$:

$$f(n) > c \cdot g(n)$$

f dominates g asymptotically

$$f(n) = \omega(g(n))$$

Limit definition:

$$\lim_{n \to \infty} \frac{f(n)}{g(n)} = \infty$$

Example of Small ω

 $f(n) = \omega(g(n)) \colon$ the order of f(n) is strictly larger than that of g(n)

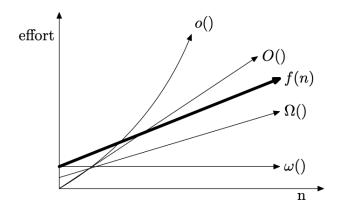
Typical usage. $n = \omega(\log n)$

Example. $f(n) = n^2 + n$, $f(n) = \omega(n)$

- $\lim_{n\to\infty} \frac{f(n)}{n} = \infty$
- $f(n) \neq \omega(n^2)$: choose c=2, there does not exist n_0 such that $\forall n \geq n_0$

$$cn^2 = 2n^2 < n^2 + n$$

Visualize the Relationships between these notations



Comparisons

Notation	? c > 0	$? n_0$	$f(n) ? c \cdot g(n)$	meaning
O	∃	3	<u> </u>	upper bound
О	\forall	3	<	non-tight upper bound
Ω	3	3	<u> </u>	lower bound
ω	A	3	>	non-tight lower bound

While o and ω are not often used to described algorithms

• We define a combination of O and Ω : Θ , which means g(n) is both a tight upper-bound and a tight lower-bound

Big-⊖ **Notation:** Aims to a **Tight Bound**

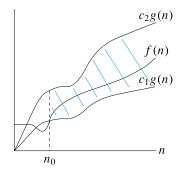
Definition 7 (Big- Θ)

 $\exists c_1>0$, $\exists c_2>0$, $\exists n_0$, such that $\forall n>n_0$

$$c_1 \cdot g(n) \le f(n) \le c_2 \cdot g(n)$$

f is bounded both above and below by g asymptotically

$$f(n) = \Theta(g(n))$$



Limit definition

$$\lim_{n \to \infty} \frac{f(n)}{g(n)} = c$$

Proof of Equivalence

Proof. Definition of the limit $\Rightarrow \forall \varepsilon > 0$, $\exists n_0, \forall n \geq n_0$:

$$|f(n)/g(n) - c| < \varepsilon$$

 $c - \varepsilon < f(n)/g(n) < c + \varepsilon$

Proof of Equivalence

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$$|f(n)/g(n) - c| < \varepsilon$$

 $c - \varepsilon < f(n)/g(n) < c + \varepsilon$

choose
$$\varepsilon = c/2 \Rightarrow c/2 < f(n)/g(n) < 3c/2$$

- $\forall n \ge n_0, f(n) \le (3c/2)g(n) \Rightarrow f(n) = O(g(n))$
- $\forall n \ge n_0, f(n) \ge (c/2)g(n) \Rightarrow f(n) = \Omega(g(n)).$

Proof of Equivalence

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$$\varepsilon = c/2 \Rightarrow c/2 < f(n)/g(n) < 3c/2$$

- $\forall n \geq n_0$, $f(n) \leq (3c/2)g(n) \Rightarrow f(n) = O(g(n))$
- $\forall n \geq n_0, \ f(n) \geq (c/2)g(n) \Rightarrow f(n) = \Omega(g(n)).$

This proves $f(n) = \Theta(g(n))$

More about Big- Θ

$$f(n) = \Theta(g(n)) \colon f(n) = O(g(n)) \land f(n) = \Omega(g(n)), \ f(n)$$
 and $g(n)$ have the same order

Typical usage:

• Mergesort makes $\Theta(n \log n)$ compares to sort n elements.

Example 1.
$$f(n) = n^2 + n$$
, $g(n) = 100n^2$
$$f(n) = \Theta(g(n))$$

Example 2. $f(n) = 32n^2 + 17n + 1$

- f(n) is $\Theta(n^2) \leftarrow$ choose $c_1 = 32$, $c_2 = 50$, $n_0 = 1$
- f(n) is neither $\Theta(n)$ nor $\Theta(n^3)$

Example of Primality Test

Algorithm 6: PrimalityTest(n)

Input: odd integer n>2

Output: true or false

- 1: $s \leftarrow \lfloor n^{1/2} \rfloor$;
- 2: for $j \leftarrow 2$ to s do
- 3: **if** j divides n then return false;
- 4: **end**
- 5: return true;

Example of Primality Test

Algorithm 7: PrimalityTest(n)

```
Input: odd integer n>2
```

Output: true or false

- 1: $s \leftarrow \lfloor n^{1/2} \rfloor$;
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If $n^{1/2}$ is computable in ${\cal O}(1)$ -time, the basic operation is divide

Example of Primality Test

Algorithm 8: PrimalityTest(n)

Input: odd integer n>2

Output: true or false

- 1: $s \leftarrow \lfloor n^{1/2} \rfloor$;
- 2: for $j \leftarrow 2$ to s do
- 3: **if** j divides n then return false;
- 4: end
- 5: return true;

If $n^{1/2}$ is computable in O(1)-time, the basic operation is divide What is the worst-case complexity of naive primality test?

Input Size Matters: Case of Primality Test

Using n as input size of $W(\cdot)$

$$W(n) = O(n^{1/2})$$
 \checkmark $W(n) = \Omega(n^{1/2})$ \checkmark

• Consider inputs of the form 3m, then $n^{1/2}$ is not the lower bound

Using λ as input size (length of binary representation of n) of $W(\cdot)$.

$$W(n) = O(2^{\lambda/2}) \checkmark W(n) = \Omega(2^{\lambda/2}) \checkmark$$
 a.k.a. $W(\lambda) = \Theta(2^{\lambda/2})$

Input size aims to capture the scale of a class of instances. This is what make this notion useful. For the first case, a class of instance degrades to a single instance, thus making worst-case complexity meaningless.

Big-*O* notation with multiple variables

Upper bounds. f(m,n) is O(g(m,n)) if $\exists c>0$, $m_0\geq 0$ and $n_0\geq 0$ such that $\forall n\geq n_0$ and $m\geq m_0$, $f(m,n)\leq c\cdot g(m,n)$

Example. $f(m,n) = 32mn^2 + 17mn + 32n^3$

- f(m,n) is both $O(mn^2 + n^3)$ and $O(mn^3)$
- f(m,n) is neither $O(n^3)$ nor $O(mn^2)$

Typical usage. Breadth-first search takes O(m+n) time to find the shortest path from s to t in a digraph

Transitivity. The order of functions are transitive.

•
$$f = O(g) \land g = O(h) \Rightarrow f = O(h)$$

$$\bullet \ f = \Omega(g) \wedge g = \Omega(h) \Rightarrow f = \Omega(h)$$

$$\bullet \ f = \Theta(g) \wedge g = \Theta(h) \Rightarrow f = \Theta(h)$$

•
$$f = o(g) \land g = o(h) \Rightarrow f = o(h)$$

•
$$f = \omega(g) \land g = \omega(h) \Rightarrow f = \omega(h)$$

Product

- $f_1 = O(g_1) \land f_2 = O(g_2) \Rightarrow f_1 f_2 = O(g_1 g_2)$
- $\bullet \ f \cdot O(g) = O(fg)$

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Sum

- $f_1 = O(g_1) \land f_2 = O(g_2) \Rightarrow f_1 + f_2 = O(\max(g_1, g_2))$
- This implies $f_1 = O(g) \land f_2 = O(g) \Rightarrow f_1 + f_2 \in O(g)$, which means that O(g) is a <u>convex cone</u>.

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This property extends to a finite composition of f_i

• Application. For an algorithm, if the running time of its each step is upper bounded by h(n), and the algorithm only consists of constant steps, then the overall complexity is O(h(n)).

Product

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- This implies $f_1 = O(g) \land f_2 = O(g) \Rightarrow f_1 + f_2 \in O(g)$, which means that O(g) is a <u>convex cone</u>.

This property extends to a finite composition of f_i

• Application. For an algorithm, if the running time of its each step is upper bounded by h(n), and the algorithm only consists of constant steps, then the overall complexity is O(h(n)).

Multiplication by a constant. Let k > 0 be a constant. Then:

- O(kg) = O(g), if $k \neq 0$.
- $f = O(g) \Rightarrow kf = O(g)$ (multiplicative constants can be omitted)

Outline

- Notions of Algorithm and Time Complexity
- Pseudocode of Algorithm
- 3 Asymptotic Order of Function
- 4 Important Function Class
- 5 Survey of Common Running Times

Important Function Classes (increasing order)

We list important function class in ascending order

- constant: O(1)
- ullet double logarithmic: $\log \log n$
- logarithmic: $\log n$
- polylogarithmic: $(\log n)^c$, c > 1
- fractional power: n^c , 0 < c < 1
- linear: O(n)
- loglinear or quasilinear: $n \log n$
- polynomial: n^c , c > 1 (quadratic: n^2 , cubic n^3)
- exponential: c^n , c > 1
- factorial: n!

Asymptotic Bounds for some Common Functions (1/3)

Technical tool. Limit Definitions of $O, \Omega, \Theta, o, \omega$

Polynomials. Let
$$f(n) = a_0 + a_1 n + \cdots + a_d n^d$$
, then $f(n) = \Theta(n^d)$.

Proof.

$$\lim_{n\to\infty}\frac{a_0+a_1n+\cdots+a_dn^d}{n^d}=a_d>0$$

Example. Let $f(n) = n^2/2 - 3n$, $f(n) = \Theta(n^2)$.

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Logarithms. $\Theta(\log_a n) \sim \Theta(\log_b n)$ for any constants a, b > 0

• no need to specify base (assuming it is a constant)

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Logarithms vs. Polynomials. $\forall d > 1$, $\log n = o(n^d)$.

Proof.

- Both $\lim_{n\to\infty} \ln n = \infty$ and $\lim_{n\to\infty} n^d = \infty$ and are differentiable:
- Apply L'Hôpital (Bernoulli) rule once

$$\begin{split} \lim_{n \to \infty} \frac{\ln n}{n^d} &= \lim_{n \to \infty} \frac{1/n}{dn^{d-1}} \\ &= \lim_{n \to \infty} \frac{1}{dn^d} = 0 \end{split}$$

Asymptotic Bounds for some Common Functions (3/3)

Exponentials vs. Polynomials. $\forall c > 1$ and $\forall d > 0$, $n^d = o(c^n)$.

Asymptotic Bounds for some Common Functions (3/3)

Exponentials vs. Polynomials. $\forall c > 1$ and $\forall d > 0$, $n^d = o(c^n)$.

Proof. W.L.O.G, choose d as a positive integer,

- Both $\lim_{n\to\infty} n^d = \infty$ and $\lim_{n\to\infty} c^n = \infty$ and are differentiable.
- Apply L'Hôpital (Bernoulli) rule repeatedly until the numerator is constant

$$\lim_{n \to \infty} \frac{n^d}{c^n} = \lim_{n \to \infty} \frac{dn^{d-1}}{c^n \ln c} = \lim_{n \to \infty} \frac{d(d-1)n^{d-2}}{c^n (\ln c)^2}$$
$$= \dots = \lim_{n \to \infty} \frac{d!}{c^n (\ln c)^d} = 0$$

Stirling Formula (named after James Stirling, though it was first stated by Abraham de Moivre)

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Precise form:

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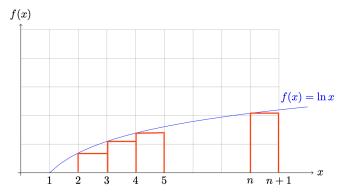
Simple form:

$$\ln n! = n \ln n - n + O(\ln n)$$

- $n! = o(n^n)$
- $n! = \omega(2^n)$
- $\ln n! = \Theta(n \ln n)$ (integral method)

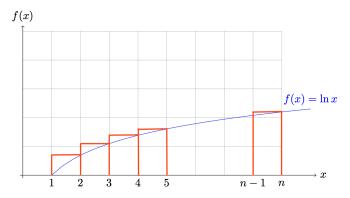
Proof of the Upper Bound

$$\ln n! = \sum_{k=1}^{n} \ln k \le \int_{2}^{n+1} \ln x dx$$
$$= (x \ln x - x)_{2}^{n+1}$$
$$= O(n \ln n)$$



Proof of the Lower Bound

$$\ln n! = \sum_{k=1}^{n} \ln k \ge \int_{1}^{n} \ln x dx$$
$$= (x \ln x - x)_{1}^{n}$$
$$= n \ln n - n + 1 = \Omega(n \ln n)$$



Application: Estimate the Size of Search Space

Recall the ROI optimization problem: the number of different investment schemes: m coins on n projects

$$C_{m+n-1}^{m} = \frac{(m+n-1)!}{m!(n-1)!}$$

$$= \frac{\sqrt{2\pi(m+n-1)}(m+n-1)^{m+n-1}\left(1+\Theta\left(\frac{1}{m+n-1}\right)\right)}{\sqrt{2\pi m}m^{m}\left(1+\Theta\left(\frac{1}{m}\right)\right)\sqrt{2\pi(n-1)}(n-1)^{n-1}\left(1+\Theta\left(\frac{1}{n-1}\right)\right)}$$

$$= \Theta((1+\varepsilon)^{m+n-1})$$

Rounding Function

Rounding a number means replacing it with a different number that is *approximately equal* to the original, but has a *shorter*, *simpler* representation

- round down (or take the floor) $y = \mathsf{floor}(x) = \lfloor x \rfloor \colon y \text{ is the largest integer that does not exceed } x$
- round up (or take the ceiling) $y=\mathrm{ceil}(x)=\lceil x\rceil\colon y \text{ is the smallest integer that is not less than } x$

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Example.
$$\lfloor 2.6 \rfloor = 2$$
, $\lceil 2.6 \rceil = 3$, $\lfloor 2 \rfloor = \lceil 2 \rceil = 2$

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Application. When performing binary search in A[n], the index of median is $\lfloor n/2 \rfloor$, the subproblem is of size $\lfloor n/2 \rfloor$.

Properties of Rounding Function

Proposition 1.
$$x - 1 < \lfloor x \rfloor \le x \le \lceil x \rceil < x + 1$$

Proof. We proof this by considering two cases:

- ② $\exists n \in \mathbb{Z}$ such that n < x < n+1, definition of rounding function $\Rightarrow \lfloor x \rfloor = n$, $\lceil x \rceil = n+1$

Proposition 2. Let $n, a, b \in \mathbb{Z}$, we have:

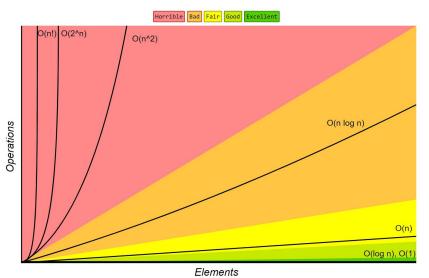
$$\lfloor x + n \rfloor = \lfloor x \rfloor + n, \lceil x + n \rceil = \lceil x \rceil + n$$

$$\lceil \frac{n}{2} \rceil + \lfloor \frac{n}{2} \rfloor = n$$

$$\lceil \frac{\lceil \frac{n}{a} \rceil}{b} \rceil = \lceil \frac{n}{ab} \rceil, \lfloor \frac{\lfloor \frac{n}{a} \rfloor}{b} \rfloor = \lfloor \frac{n}{ab} \rfloor$$

Running Times

Big-O Complexity Chart



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Common Running Times (1/4)

Constant time.
$$T(n) = O(1)$$

- Determine if a binary number is even or odd
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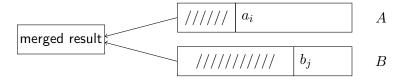
Fractional power.
$$T(n) = n^{1/2}$$

Primality test

Common Running Times (2/4)

Linear time. T(n) = O(n): running time is proportional to input size

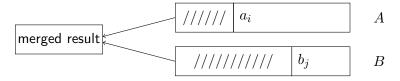
• Merge: combine two sorted lists $A = a_1, \ldots, a_n$ with $B = b_1, \ldots, b_n$ into sorted whole



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After each compare, the length of output list increases by at least 1. When one list is empty, the rest part of another list is directly merged to the result list.

• Upper bound: 2n-1 vs. Lower bound: n

Common Running Times (3/4)

Loglinear time. $T(n) = O(n \log n)$ (arises in divide-and-conquer algorithms)

- \bullet Mergesort and heapsort are sorting algorithms that perform $O(n\log n)$ compares
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• Closest pair of points. Given a list of n points in the plane $(x_1,y_1),\ldots,(x_n,y_n)$, find the pair that is closest. $O(n^2)$ solution: try all pairs of points

Remark. $\Omega(n^2)$ seems inevitable, but this is just an illusion.

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Cubic time. Enumerate all triples of elements

• Plain Matrix multiplication: $\mathbf{A}_{n\times n} \times \mathbf{B}_{n\times n}$: each $c_{i,j}$ requires O(n) multiplications, totally n^2 elements in $\mathbf{C}_{n\times n}$

Common Running Times (4/4)

Polynomial time. $T(n) = O(n^k)$

- Independent set of size k: Given a graph of n nodes, are there k nodes such that no two are joined by an edge?
- enumerate all subsets of k nodes then check
 - check if S_k is an independent set takes $O(k^2)$ time
 - $\bullet \ \#(S_k) = C_n^k \le n^k/k!$
- $O(k^2n^k/k!) = O(n^k)$ (poly-time for k = 17, but not practical)

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Exponential time. $T(n) = O(c^n)$

- Independent set: Given a graph, what is the maximum cardinality of an independent set?
- Enumerate all subsets and check: $O(n^22^n)$

Desirable scaling property. When the input size doubles, the algorithm should only slow down by some constant factor c.

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We say that an algorithm is efficient if has a polynomial running time.

Exceptions. Some poly-time algorithms do have high constants and/or exponents, and/or \rightsquigarrow useless in practice.

Question. Which would you prefer $20n^{100}$ vs. $n^{1+0.02\ln n}$

Summary of This Lecture (1/2)

Introduce abstract definition of algorithm

How to capture algorithm's complexity?

 First simplification: functions that express number of basic computer steps of input size,

How to compare functions?

 Second simplification: Big-O notations (five standard asymptotic notations) capture order of functions. We study the definitions, typical usages, examples, properties

Big-O notations lets us focus on the big picture.

• Helpful analog: $O(\leq)$, $\Omega(\geq)$, $\Theta(=)$, $o(\ll)$, $\omega(\gg)$

Summary of This Lecture (1/2)

Study important running time functions and classical algorithm examples.

Notation abuses. O(g(n)) is a set of functions, but computer scientists often write f(n) = O(g(n)) instead of $f(n) \in O(g(n))$.

Bottom line. OK to abuse notation; not OK to misuse it.

Don't misunderstand this cavalier attitude towards constants. Programmers are very interested in constants and would gladly stay up nights in order to gain 5% efficiency improvement.



Figure: Theoretical breakthrough is toooooooo hard!